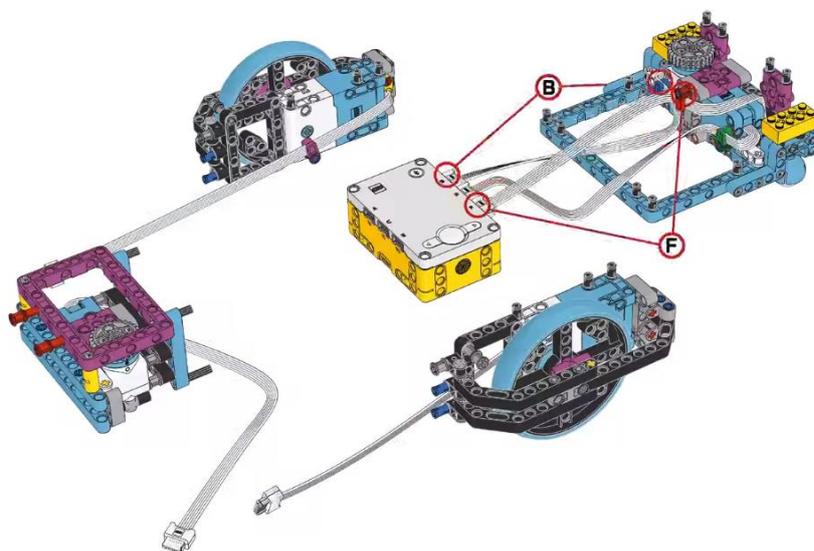
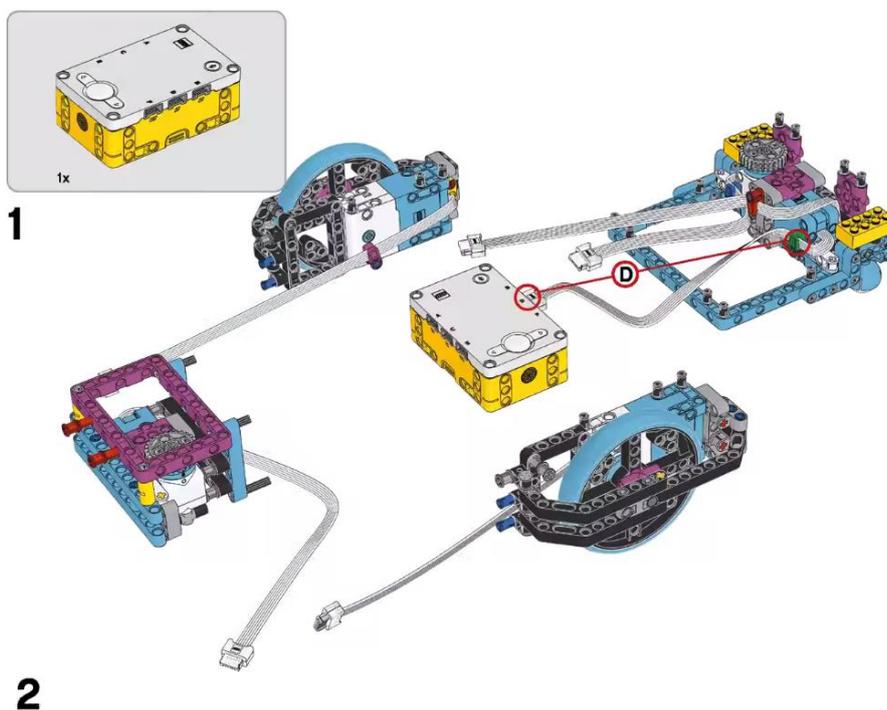
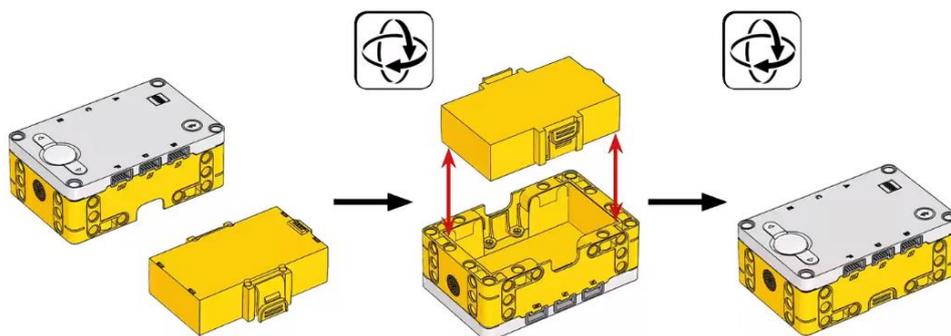
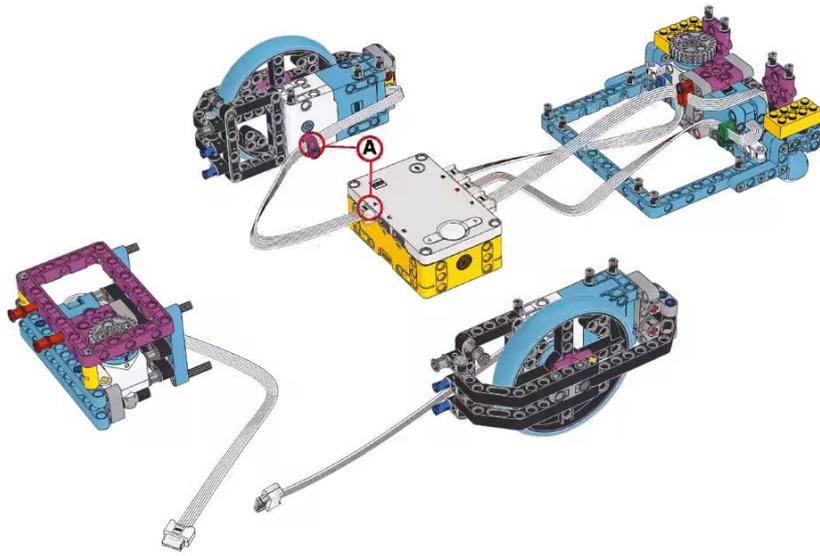


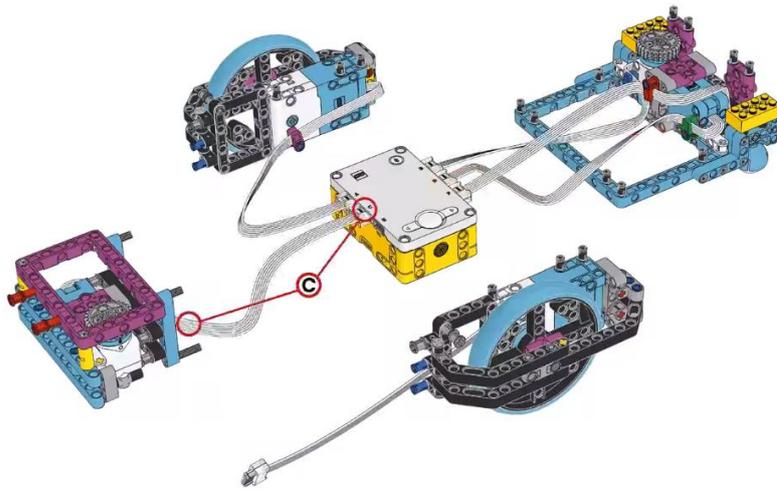
# Capítulo 11 (Mecanismos de la Base de conducción avanzada)



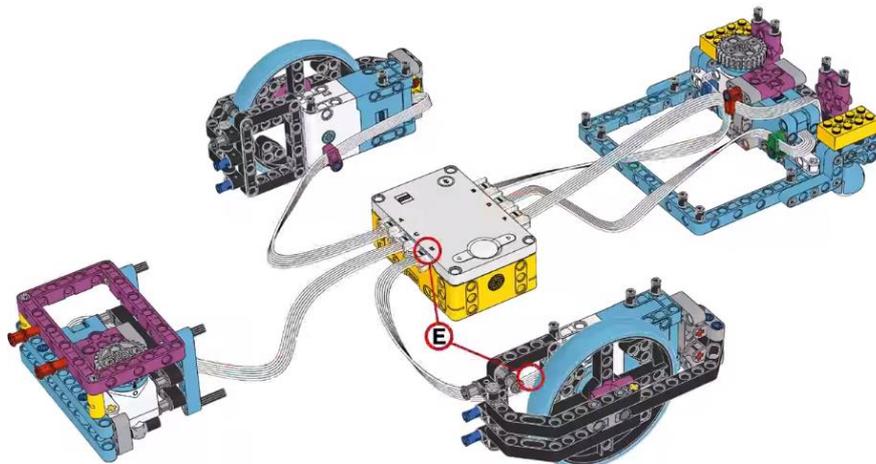
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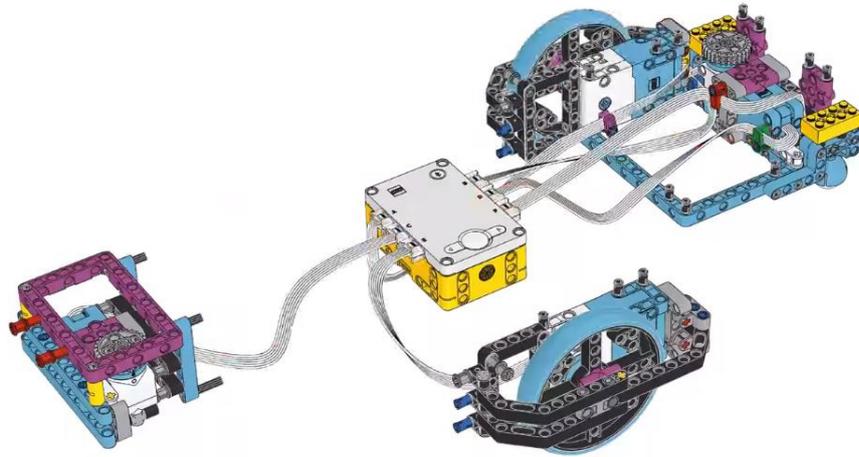
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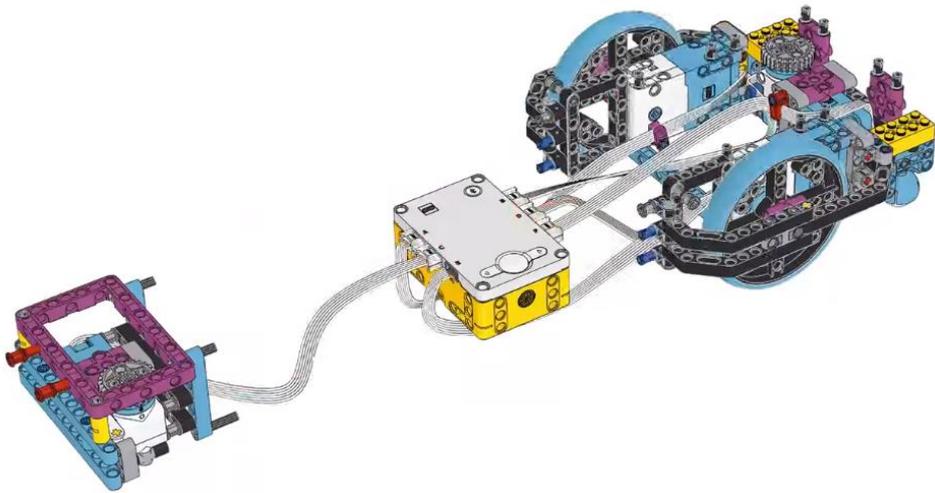
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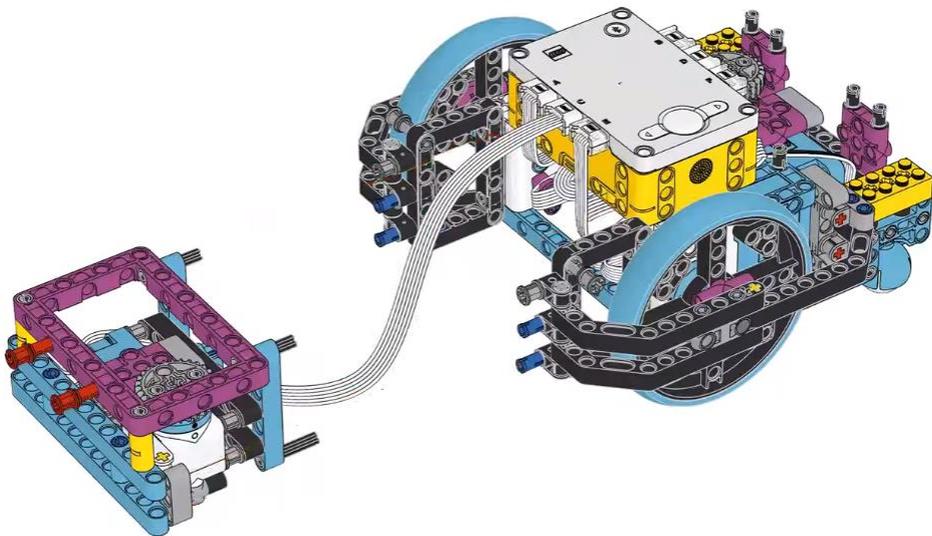
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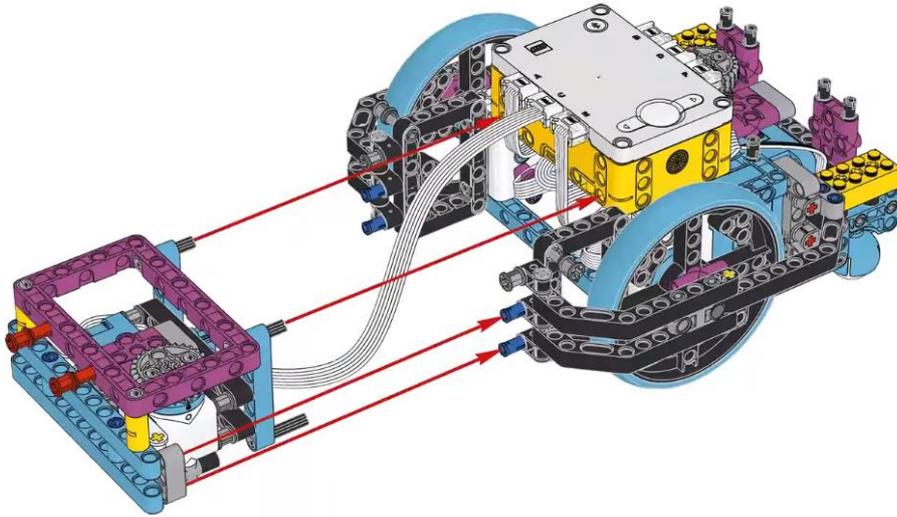
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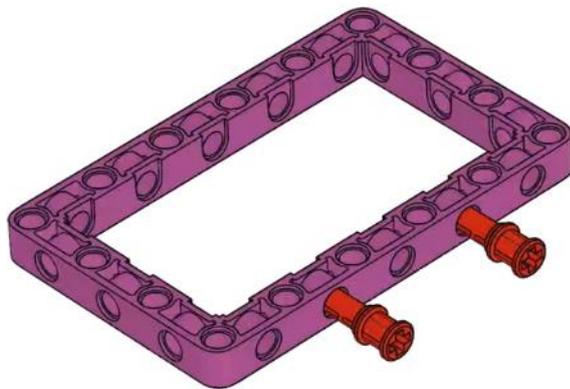
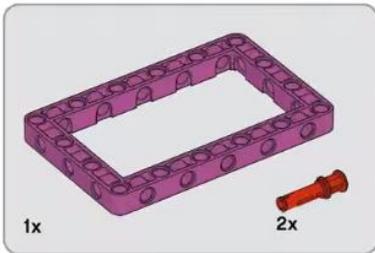
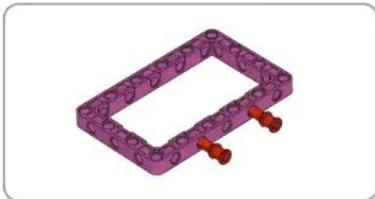
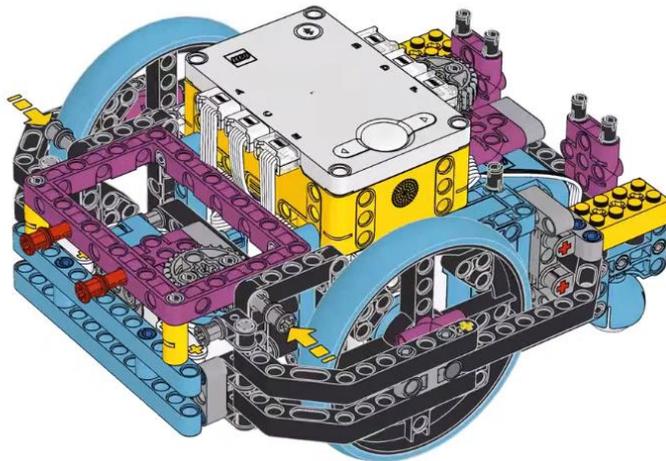
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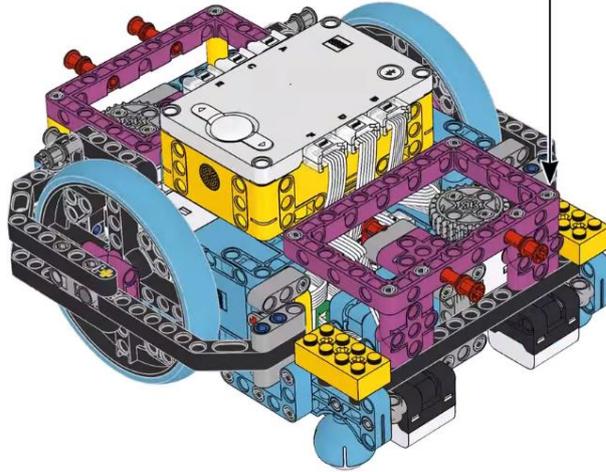


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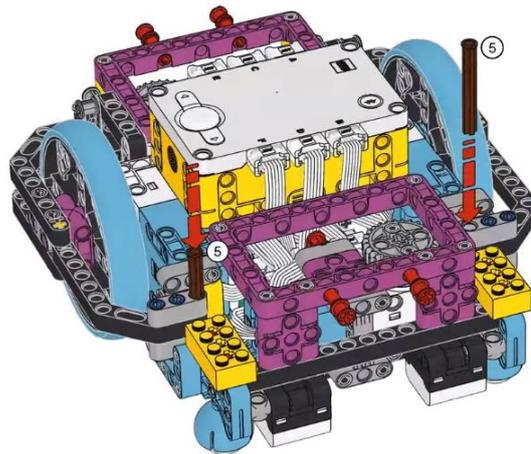


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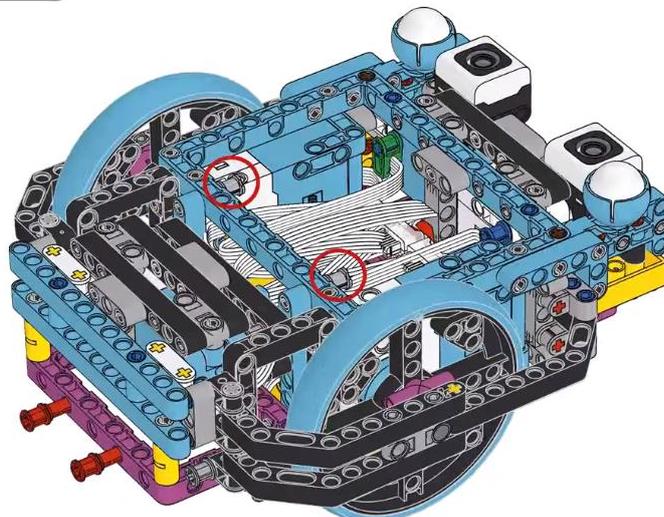
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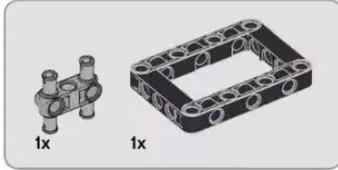


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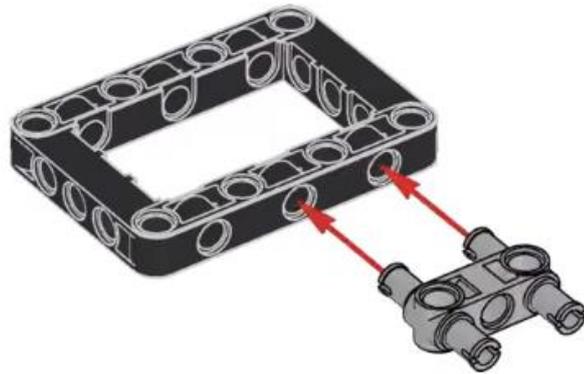


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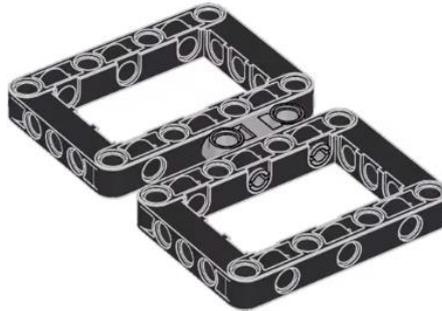




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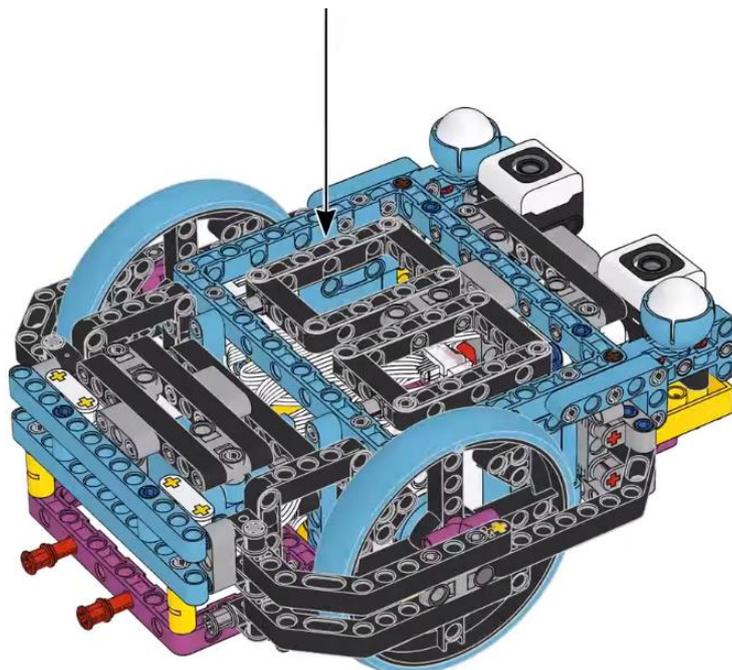
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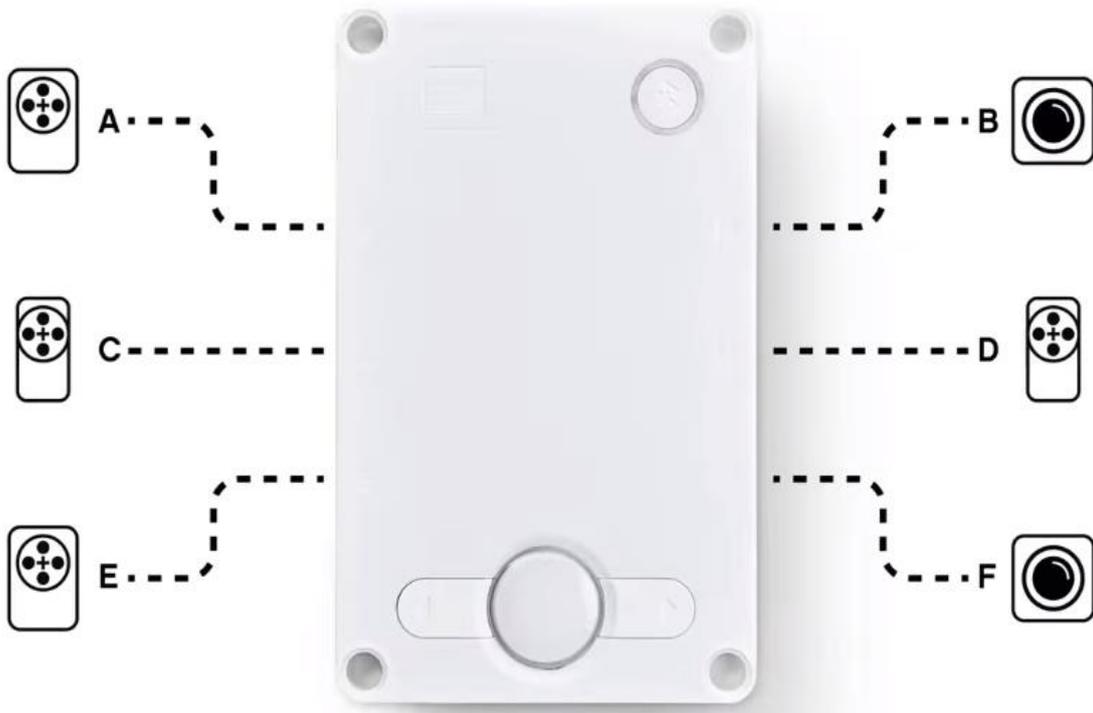
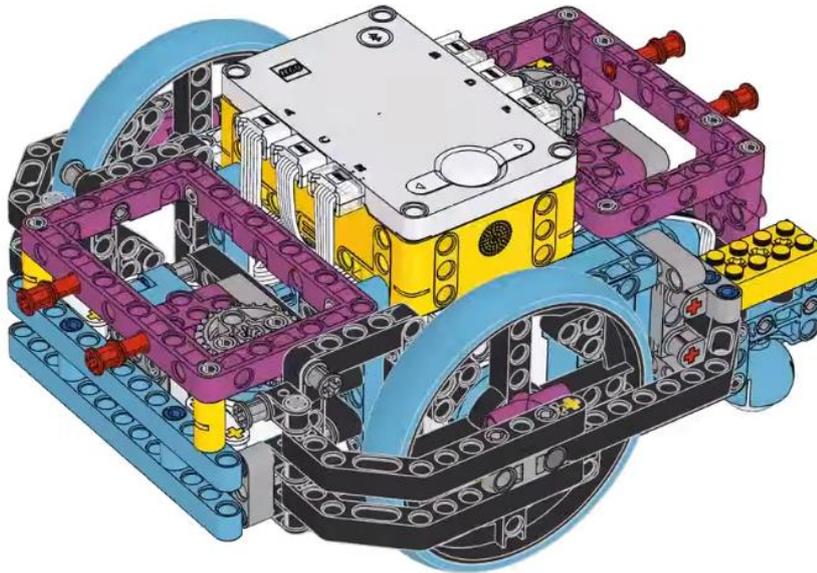
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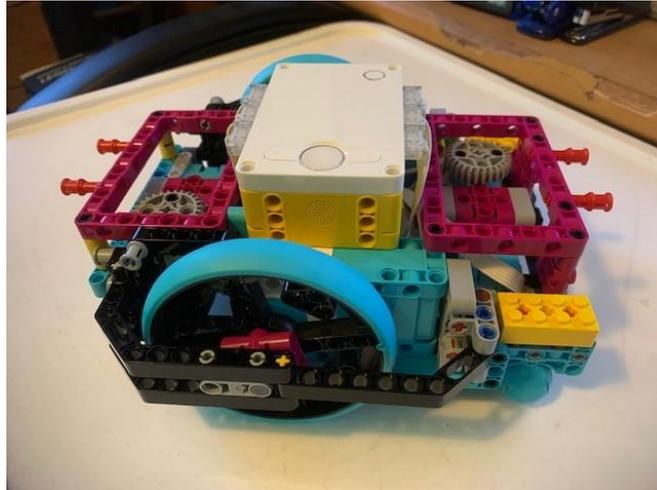


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## Codificación

Para este proyecto los valores introducidos pueden variar, según recorrido y luminosidad.

Fijar motores de movimiento a A + E

Fijar velocidad de movimiento al 10%

Bucle infinito

Si sensor conectado puerto B detecta color blanco y sensor conectado puerto F detecta color blanco.

Empezar a mover línea recta.

Si sensor de color conectado puerto B detecta color negro.

Empezar mover izquierda a -85

Si sensor de color conectado puerto F detecta color negro.

Empezar mover derecha a 86

En el siguiente código QR verás cómo tiene que actuar nuestro robot.



En la siguiente página tienes el código:

